**Project Overview:**
A system has been created that allows one user to control multiple vehicles of different operating environments separately as well as in tandem. The system utilizes a heads up display for sensor information and hand gesture control of each vehicle. A typical joystick and button controller is no longer needed which allows the user to keep their hands free to perform other tasks.

**Operating Modes:**

**Single Vehicle Selection**
- Use voice commands interpreted by HoloLens to select desired vehicle
- Hand gestures interpreted by MYO and relayed as movement commands

**Tank**
- 4 basic movement
  - Turn right/left
  - Forward
  - Backward

**Drone**
- Same basic movements as tank
- Altitude controlled by voice commands interpreted by HoloLens

**Tandem Vehicle Operation**
- The Drone will fly directly above the Tank
- Using object tracking the drone will maintain its position over the tank as the tank moves

**Technology:**

**MYO armband**
- COTS product that uses 8 sEMG sensors
- 5 pre-programmed hand gestures that can be recognized and assigned to tasks

**Microsoft HoloLens**
- HUD displays vehicle and environmental information
- Interprets voice commands

**Parrot Drone AR 2.0**
- This quadcopter comes with an easily accessible API that allows for implementation of custom control systems and add on features

**Devastator Tank Model**
- COTS product designed to be controlled by a Raspberry Pi
- Includes 2 DC motors that drive track wheels encased in an aluminum shell

**Fitting all the Pieces Together:**

**Admin Client**
- Can be used by a third party to control either of the vehicles
- All information sent to the HUD can be viewed in the admin client
- Includes kill switches for both vehicles

*Information flow diagram showing how the devices communicate with each other*