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An elliptic equation with spike solutions concentrating at local minima of the Laplacian of the potential *

Gregory S. Spradlin

Abstract

We consider the equation $-\epsilon^2 \Delta u + V(z)u = f(u)$ which arises in the study of nonlinear Schrödinger equations. We seek solutions that are positive on \mathbb{R}^N and that vanish at infinity. Under the assumption that f satisfies super-linear and sub-critical growth conditions, we show that for small ϵ there exist solutions that concentrate near local minima of V . The local minima may occur in unbounded components, as long as the Laplacian of V achieves a strict local minimum along such a component. Our proofs employ variational mountain-pass and concentration compactness arguments. A penalization technique developed by Felmer and del Pino is used to handle the lack of compactness and the absence of the Palais-Smale condition in the variational framework.

1 Introduction

This paper concerns the equation

$$-\epsilon^2 \Delta u + V(z)u = f(u) \tag{1.1}$$

on \mathbb{R}^N with $N \geq 1$, where $f(u)$ is a “superlinear” type function such as $f(u) = u^p$, $p > 1$. Such an equation arises when searching for standing wave solutions of the nonlinear Schrödinger equation (see [3]). For small positive ϵ , we seek “ground states,” that is, positive solutions u with $u(z) \rightarrow 0$ as $|z| \rightarrow \infty$. Floer and Weinstein ([6]) examined the case $N = 1$, $f(u) = u^3$ and found that for small ϵ , a ground state u_ϵ exists which concentrates near a non-degenerate critical point of V . Similar results for $N > 1$ were obtained by Oh in [10]-[12]. In [3], del Pino and Felmer found that if V has a strict local minimum, then for small ϵ , (1.1) has a ground state concentrating near that minimum. A strict local minimum occurs when there exists a bounded, open set $\Lambda \subset \mathbb{R}^N$

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with $\inf_{\Lambda} V < \inf_{\partial\Lambda} V$. They extended their results in [4] to the more general case where V has a “topologically stable” critical point, that is, a critical point obtained via a topological linking argument (see [4] for a precise formulation). Such a critical point persists under small perturbations of V . Examples are a strict local extremum and a saddle point. This very strong result is notable because the critical points of V in question need not be non-degenerate or even isolated. Similar results have been obtained by Li [8], and earlier work of Rabinowitz [13] is also interesting. The recent results of [1] and [9] also permit V to have degenerate critical points.

A common feature of all the papers above is that V must have a non-degenerate, or at least topologically stable, set of critical points. Therefore it is natural to try to remove this requirement. That we must assume some conditions on V is shown by Wang’s counterexample [15] - if V is nondecreasing and nonconstant in one variable (e.g. $V(x_1, x_2, x_3) = 2 + \tan^{-1}(x_1)$), then no ground states exist. In [14] the author showed that ground states to (1.1) exist under the assumption that V is almost periodic, together with another mild assumption. Those assumptions did not guarantee that V had a topologically stable critical point.

Aside from periodicity or recurrence properties of V , another approach is to impose conditions on the derivatives of V . That is the approach taken here. We will assume that V has a (perhaps unbounded) component of local minima, along which ΔV achieves a strict local minimum. More specifically, assume f satisfies the following:

$$(F1) \quad f \in C^1(\mathbb{R}^+, \mathbb{R})$$

$$(F2) \quad f'(0) = 0 = f(0).$$

$$(F3) \quad \lim_{q \rightarrow \infty} f(q)/q^s = 0 \text{ for some } s > 1, \text{ with } s < (N+2)/(N-2) \text{ if } N \geq 3.$$

$$(F4) \quad \text{For some } \theta > 2, 0 < \theta F(q) \leq f(q)q \text{ for all } q > 0, \text{ where } F(\xi) \equiv \int_0^\xi f(t) dt.$$

$$(F5) \quad \text{The function } q \mapsto f(q)/q \text{ is increasing on } (0, \infty).$$

Assumptions (F1)-(F5) are the same as in [3] and are satisfied by $f(q) = q^s$, for example, if $1 < s < (N+2)/(N-2)$. Assume that V satisfies the following:

$$(V1) \quad V \in C^2(\mathbb{R}^n, \mathbb{R})$$

$$(V2) \quad D^\alpha V \text{ is bounded and Lipschitz continuous for } |\alpha| = 2.$$

$$(V3) \quad 0 < V_- \equiv \inf_{\mathbb{R}^N} V < \sup_{\mathbb{R}^N} V \equiv V^+ < \infty$$

$$(V4) \quad \text{There exists a bounded, nonempty open set } \Lambda \subset \mathbb{R}^N \text{ and a point } z_0 \in \Lambda \text{ with } V(z_0) = \inf_{\Lambda} V \equiv V_0, \text{ and}$$

$$\Delta_0 \equiv \inf\{\Delta V(z) \mid z \in \Lambda, V(z) = V_0\} < \inf\{\Delta V(z) \mid z \in \partial\Lambda, V(z) = V_0\}$$

Note: A special case of (V4) occurs when Λ is bounded and $V(z_0) < \inf_{\partial\Lambda} V$; this case is treated, under weaker hypotheses, in [3]. A specific example of (V4) is if $N = 2$ and V satisfies (V1)-(V4), with $V(z_1, z_2) = 1 + (z_1^2 - z_2)^2$ for $z_1^2 + z_2^2 \leq 1$. Then $\Delta V(z_1, z_1^2) = 8z_1^2 + 2$ for $z_1^2 + z_2^2 \leq 1$, so we may take $\Lambda = B_1(0, 0) \subset \mathbb{R}^2$ and $z_0 = (0, 0)$. Then V has a component of local minima that includes the parabolic arc $\{z_2 = z_1^2\} \cap B_1(0, 0)$, along which ΔV has a minimum of 2 at $(0, 0)$, with $\Delta V > 2$ at the two endpoints of the arc.

We prove the following:

Theorem 1.1 *Let V and f satisfy (V1)-(V4) and (F1)-(F5). Then there exists $\epsilon_0 > 0$ such that if $\epsilon \leq \epsilon_0$, then (1.0) has a positive solution u_ϵ with $u_\epsilon(z) \rightarrow 0$ as $|z| \rightarrow \infty$. u_ϵ has exactly one local maximum (hence, global maximum) point $z_\epsilon \in \Lambda$, where Λ is as in (V4). There exist $\alpha, \beta > 0$ with $u_\epsilon(z) \leq \alpha \exp(-\frac{\beta}{\epsilon}|z - z_\epsilon|)$ for $\epsilon \leq \epsilon_0$. Furthermore, with V_0 and Δ_0 as in (V4), $V(z_\epsilon) \rightarrow V_0$ and $\Delta V(z_\epsilon) \rightarrow \Delta_0$ as $\epsilon \rightarrow 0$.*

For small ϵ , u_ϵ resembles a “spike,” which is sharper for smaller ϵ . The spike concentrates near a local minimum of V where ΔV has a strict local minimum. The proof of Theorem 1.1 employs the techniques of [3], with some refinements necessary because V does not necessarily achieve a *strict* local minimum. Section 2 introduces the penalization scheme developed by Felmer and del Pino, and continues with the beginning of the proof of Theorem 1.1. These beginning arguments are taken practically verbatim from [3], but are included, since the machinery of the penalization technique is used in the remainder of the proof. The reader is invited to consult [3] for more complete proofs. Section 3 contains the completion of the proof, which is original. This part contains delicate computations involving ΔV .

2 The penalization scheme

Extend f to the negative reals by defining $f(q) = 0$ for $q < 0$. Let F be the primitive of f , that is, $F(q) = \int_0^q f(t) dt$. Define the functional I_ϵ on $W^{1,2}(\mathbb{R}^N)$ by

$$I_\epsilon(u) = \int_{\mathbb{R}^N} \frac{1}{2}(\epsilon^2 |\nabla u|^2 + V(z)u^2) - F(u) dz.$$

I_ϵ is a C^1 functional, and there is a one-to-one correspondence between positive critical points of I_ϵ and ground states of (1.1). It is well known that I_ϵ and similar functionals in related problems fail the Palais-Smale condition. That is, a “Palais-Smale sequence,” defined as a sequence (u_m) with $I_\epsilon(u_m)$ convergent and $I'_\epsilon(u_m) \rightarrow 0$ as $m \rightarrow \infty$, need not have a convergent subsequence. To get around this difficulty, we formulate a “penalized” problem, with a corresponding “penalized” functional satisfying the Palais-Smale condition, by altering f outside of Λ .

Let θ be as in (F4). Choose k so $k > \theta/(\theta - 2)$. Let V_- be as in (V3) and $a > 0$ be the value at which $f(a)/a = V_-/k$. Define \tilde{f} by

$$\tilde{f}(s) = \begin{cases} f(s) & s \leq a; \\ sV_-/k & s > a, \end{cases} \quad (2.1)$$

$g(\cdot, s) = \chi_\Lambda f(s) + (1 - \chi_\Lambda)\tilde{f}(s)$, and $G(z, \xi) = \int_0^\xi g(z, \tau) d\tau$. Although not continuous, g is a Carathéodory function. For $\epsilon > 0$, define the penalized functional J_ϵ on $W^{1,2}(\mathbb{R}^N)$ by

$$J_\epsilon(u) = \int_{\mathbb{R}^N} \frac{1}{2}(\epsilon^2|\nabla u|^2 + V(z)u^2) - G(z, u) dz. \quad (2.2)$$

A positive critical point of J_ϵ is a weak solution of the “penalized equation”

$$-\epsilon^2\Delta u + V(z)u = g(z, u), \quad (2.3)$$

that is, a C^1 function satisfying (2.3) wherever g is continuous. It is proven in [3] that J_ϵ satisfies all the hypotheses of the Mountain Pass Theorem of Ambrosetti and Rabinowitz ([2]), including the Palais-Smale condition. Therefore J_ϵ has a critical point u_ϵ , with the mountain pass critical level $c(\epsilon) = J_\epsilon(u_\epsilon)$. $c(\epsilon)$ is defined by the following minimax: let the set of paths $\Gamma_\epsilon = \{\gamma \in C([0, 1], W^{1,2}(\mathbb{R}^N)) \mid \gamma(0) = 0, J_\epsilon(\gamma(1)) < 0\}$, and

$$c(\epsilon) = \inf_{\gamma \in \Gamma_\epsilon} \max_{\theta \in [0, 1]} J_\epsilon(\gamma(\theta)).$$

As shown in ([3]), because of (F4), $c(\epsilon)$ can be characterized more simply as

$$c(\epsilon) = \inf_{u \in W^{1,2}(\mathbb{R}^N) \setminus \{0\}} \sup_{\tau > 0} J_\epsilon(\tau u).$$

The functions $g(z, q)$ and $f(q)$ agree whenever $z \in \Lambda$ or $q < a$. Therefore if u is a weak solution of (2.3) with $u < a$ on $\Lambda^C \equiv \mathbb{R}^N \setminus \Lambda$, then u solves (1.1). Our plan is to find a positive critical point u_ϵ of J_ϵ , which is a weak solution of (2.3), then show that $u_\epsilon(z) < a$ for all $z \in \Lambda^C$.

For $\epsilon > 0$, let u_ϵ be a critical point of J_ϵ with $J_\epsilon(u_\epsilon) = c(\epsilon)$. Maximum principle arguments show that u_ϵ must be positive. Define the “limiting functional” I_0 by

$$I_0(u) = \int_{\mathbb{R}^N} \frac{1}{2}(|\nabla u|^2 + V_0 u^2) - F(u) \quad (2.4)$$

and

$$c = \inf_{u \in W^{1,2}(\mathbb{R}^N) \setminus \{0\}} \sup_{\tau > 0} I_0(\tau u). \quad (2.5)$$

The equation corresponding to (2.4) is

$$-\Delta u + V_0 u = f(u) \quad (2.6)$$

We will prove Theorem 1.1 by proving the following proposition:

Proposition 2.1 *Let $\epsilon > 0$. If u_ϵ is a positive solution of (2.3) satisfying $J_\epsilon(u_\epsilon) = c(\epsilon)$, then*

- (i) $\lim_{\epsilon \rightarrow 0} \max_{z \in \partial\Lambda} u_\epsilon = 0$.
- (ii) *For all ϵ sufficiently small, u_ϵ has only one local maximum point in Λ (call it z_ϵ), with $\lim_{\epsilon \rightarrow 0} V(z_\epsilon) = V_0$*
- (iii) $\lim_{\epsilon \rightarrow 0} \Delta V(z_\epsilon) = \Delta_0$.

Proof of Theorem 1.1: Assuming Proposition 2.1, there exists $\epsilon_0 > 0$ such that for $\epsilon < \epsilon_0$, $u_\epsilon < a$ on $\partial\Lambda$. In [3] it is shown that if we multiply (2.3) by $(u_\epsilon - a)_+$ and integrate by parts, it follows that $u_\epsilon < a$ on Λ^C , so u_ϵ solves (1.1). By the definition of a in (2.1), and the maximum principle, u_ϵ has no local maxima outside of Λ , so u_ϵ has exactly one local maximum point z_ϵ , which occurs in Λ .

Define v_ϵ by translating u_ϵ from z_ϵ to zero and dilating it by ϵ , that is,

$$v_\epsilon(z) = u_\epsilon(z_\epsilon + \epsilon z).$$

Then v_ϵ is a weak (C^1) solution of the “translated and dilated” equation

$$-\Delta v_\epsilon + V(z_\epsilon + \epsilon z)v_\epsilon = g(z_\epsilon + \epsilon z, v_\epsilon).$$

Let $\epsilon_j \rightarrow 0$. Along a subsequence (called (z_{ϵ_j})), $z_{\epsilon_j} \rightarrow \bar{z} \in \bar{\Lambda}$, with $V(\bar{z}) = V_0$ and $\Delta V(\bar{z}) = \Delta_0$.

Along a subsequence, v_{ϵ_j} converges locally uniformly to a function v^0 . Pick $R > 0$ so $v^0 < a$ on $\mathbb{R}^N \setminus B_R(0)$. For large enough ϵ , $v_\epsilon < a$ on $\partial B_R(0)$. By the maximum principle arguments of [3], for small ϵ , v_ϵ decays exponentially, uniformly in ϵ . ◇

The proof of Proposition 2.1 will follow if we can prove the following statement.

Proposition 2.2 *If $\epsilon_n \rightarrow 0$ and $(z_n) \subset \bar{\Lambda}$ with $u_{\epsilon_n}(z_n) \geq b > 0$, then*

- (i) $\lim_{n \rightarrow \infty} V(z_n) = V_0$.
- (ii) $\lim_{n \rightarrow \infty} \Delta V(z_n) = \Delta_0$.

It is proven in [3] that u_ϵ has exactly one local maximum point z_ϵ for small ϵ . Since u_ϵ solves (2.3), the maximum principle implies that $u_\epsilon(z_\epsilon)$ is bounded away from zero. Thus Proposition 2.2 and (V4) give Proposition 2.1(ii)-(iii).

To prove Proposition 2.2, let b and (z_n) be as above. First we repeat the argument of [3] to show that $V(z_n) \rightarrow V_0$: suppose this does not happen. Then, along a subsequence, $z_n \rightarrow \bar{z} \in \bar{\Lambda}$ with $V(\bar{z}) > V_0$. Define v_n by translating u_{ϵ_n} from z_n to 0 and dilating by ϵ_n ; that is,

$$v_n(z) = u_{\epsilon_n}(z_n + \epsilon_n z). \tag{2.7}$$

v_n solves the “translated and dilated” penalized equation

$$-\Delta v_n + V(z_n + \epsilon_n z)v_n = g(z_n + \epsilon_n z, v_n) \quad (2.8)$$

on \mathbb{R}^N , with $v_n(z) \rightarrow 0$ and $\nabla v_n(z) \rightarrow 0$ as $|z| \rightarrow \infty$. As shown in [3], (v_n) is bounded in $W^{1,2}(\mathbb{R}^N)$, so by elliptic estimates, (v_n) converges locally along a subsequence (also denoted (v_n)) to $v^0 \in W^{1,2}(\mathbb{R}^N)$. Define χ_n by $\chi_n(z) = \chi_\Lambda(z_n + \epsilon_n z)$, where χ_Λ is the characteristic function of Λ . χ_n converges weakly in L^p over compact sets to a function χ , for any $p > 1$, with $0 \leq \chi \leq 1$. Define

$$\bar{g}(z, s) = \chi(z)f(s) + (1 - \chi(z))\tilde{f}(s)$$

Then v^0 satisfies

$$-\Delta v + V(\bar{z})v = \bar{g}(z, v) \quad (2.9)$$

on \mathbb{R}^N . Define $\bar{G}(z, s) = \int_0^s \bar{g}(z, t) dt$. Associated with (2.9) we have the limiting functional $\bar{J}(u) = \int_{\mathbb{R}^N} \frac{1}{2}(|\nabla u|^2 + V(\bar{z})u^2) - \bar{G}(z, u) dz$. v^0 is a positive critical point of \bar{J} .

Define J_n to be the “translated and dilated” penalized functional corresponding to (2.8), that is,

$$J_n(u) = \int_{\mathbb{R}^N} \frac{1}{2}(|\nabla u|^2 + V(z_n + \epsilon_n z)u^2) - G(z_n + \epsilon_n z, u) dz.$$

Clearly $J_n(v_n) = \epsilon_n^{-N} J_{\epsilon_n}(u_{\epsilon_n})$. In [3] it is proven that

$$\liminf_{n \rightarrow \infty} J_n(v_n) \geq \bar{J}(v^0). \quad (2.10)$$

Also, by letting w be a ground state for (2.6) with $I_0(w) = \underline{c}$ (the mountain pass value for I_0 , defined in (2.5) and using w as a test function for J_n , it is proven that $\underline{c} \geq \liminf_{n \rightarrow \infty} J_n(v_n)$). Thus $\bar{J}(v^0) \leq \underline{c}$. Therefore, as shown in [3], $V(\bar{z}) \leq V_0$. This contradicts our assumption. Thus $V(z_n) \rightarrow V_0$. All the above is the same as was proven in [3]. Next, we must show that $\Delta V(z_n) \rightarrow \Delta_0$. That is the focus of the next section.

3 The effect of the Laplacian

Proving $\Delta V(z_n) \rightarrow \Delta_0$ is a subtle and delicate problem. Making ϵ_n approach 0 is equivalent to dilating V , which has the effect of making local minima of V behave more like global minima. This assists in finding solutions to (1.1). However, making ϵ_n small *reduces* the effect of differences in ΔV . For this reason, Theorem 1.1 is not only difficult to prove, but is not intuitively compelling, either.

It is known ([7]) that a “least energy solution” of (2.6), that is, a solution w with $I_0(w) = \underline{c}$, must be radially symmetric. We will need to exploit this fact. In order to do this, we will need to work with the maximum points of u_{ϵ_n} instead of merely the (z_n) as given in Proposition 2.2. We need the following concentration-compactness result, which states that the sequence (u_{ϵ_n}) of “mountain-pass type solutions” of (2.3) does not “split”:

Lemma 3.1 *If $(z_n) \subset \bar{\Lambda}$, $(y_n) \subset \mathbb{R}^N$, and $b > 0$ with $u_{\epsilon_n}(z_n) > b$ and $u_{\epsilon_n}(y_n) > b$ for all n , then $((z_n - y_n)/\epsilon_n)$ is bounded.*

Proof: define $v_n(z) = u_{\epsilon_n}(z_n + \epsilon_n z)$ as in (2.7). Suppose the lemma is false. Then, along a subsequence, $|y_n - z_n|/\epsilon_n \rightarrow \infty$. Let $x_n = (y_n - z_n)/\epsilon_n$. ($\|v_n\|$) is bounded in $W^{1,2}(\mathbb{R}^N)$ and $|x_n| \rightarrow \infty$, so we may pick a sequence $(R_n) \subset \mathbb{N}$ with $R_n \rightarrow \infty$, $|x_n| - R_n \rightarrow \infty$, and $\|v_n\|_{W^{1,2}(B_{R_n+1}(0) \setminus B_{R_n-1}(0))} \rightarrow 0$ as $n \rightarrow \infty$. Define cutoff functions $\varphi_n^{1,2} \in C^\infty(\mathbb{R}^N, [0, 1])$ satisfying $\varphi_1 \equiv 1$ on $B_{R_n-1}(0)$, $\varphi_1 \equiv 0$ on $B_{R_n}(0)^c$, $\varphi_2 \equiv 1$ on $B_{R_n+1}(0)^c$, $\varphi_2 \equiv 0$ on $B_{R_n}(0)$, and $\|\nabla \varphi_1\|_{L^\infty(\mathbb{R}^N)} < 2$, $\|\nabla \varphi_2\|_{L^\infty(\mathbb{R}^N)} < 2$. Set $v_n^1 = \varphi_n^1 v_n$ and $v_n^2 = \varphi_n^2 v_n$, and $\bar{v}_n = v_n^1 + v_n^2 = (\varphi_n^1 + \varphi_n^2)v_n$.

Choose $T_n > 0$ so $J_n(T_n \bar{v}_n) = 0$. We claim that T_n is well-defined, and bounded in n . Note that the existence of T_n must be checked for the penalized functional J_n , because of the replacement of F with G . By elliptic estimates, there exists an open set $U \subset \mathbb{R}^N$ such that along a subsequence, $v_n^1 > b/2$ on U and $U \subset (\Lambda - z_n)/\epsilon_n \equiv \{z \in \mathbb{R}^N \mid z_n + \epsilon_n z \in \Lambda\}$. Let a be as in (2.1). For $t > 2a/b$ and $z \in U$, $t\bar{v}_n(z) > tb/2 > a$, so $G(z_n + \epsilon_n z, t\bar{v}_n) = F(t\bar{v}_n) > F(bt/2)$. Therefore, for $t > 2a/b$,

$$\begin{aligned} J_n(t\bar{v}_n) &= t^2 \int_{\mathbb{R}^N} \frac{1}{2} (|\nabla \bar{v}_n|^2 + V(z_n + \epsilon_n z) \bar{v}_n^2) dz - \int_{\mathbb{R}^N} G(z_n + \epsilon_n z, t\bar{v}_n) dz \\ &\leq \frac{t^2}{2} (1 + V^+) \|\bar{v}_n\|_{W^{1,2}(\mathbb{R}^N)}^2 - \int_U F(t\bar{v}_n) \\ &\leq \frac{t^2}{2} (1 + V^+) \|\bar{v}_n\|_{W^{1,2}(\mathbb{R}^N)}^2 - \lambda(U) F(tb/2), \end{aligned}$$

where λ indicates the Lebesgue measure. By (F4), there exists $C > 0$ such that for $t > 2a/b$, $F(tb/2) > Ct^\theta$. Therefore, for $t > 2a/b$,

$$J_n(t\bar{v}_n) \leq \frac{t^2}{2} (1 + V^+) \|\bar{v}_n\|_{W^{1,2}(\mathbb{R}^N)}^2 - Ct^\theta. \tag{3.1}$$

Since (\bar{v}_n) is bounded in $W^{1,2}(\mathbb{R}^N)$, this gives the existence and boundedness of (T_n) .

Since $J_n(T_n \bar{v}_n) = J_n(T_n v_n^1) + J_n(T_n v_n^2) = 0$, we may pick $i_n \in \{1, 2\}$ with $J_n(T_n v_n^{i_n}) \leq 0$. By (F5) and (2.1), the map $t \mapsto J_n(tv_n^{i_n})$ increases from zero at $t = 0$, achieves a positive maximum, then decreases to $-\infty$. We will see more of this in a moment. Thus there exists a unique $t_n \in (0, T_n)$ with $J_n(t_n v_n^{i_n}) = \max_{t>0} J_n(tv_n^{i_n})$. We claim that t_n and $T_n - t_n$ are both bounded away from zero for large n : by $(f_1) - (f_4)$ and (2.1), $J_n(w) \geq \frac{1}{\theta} \min(1, V_-) \|w\|_{W^{1,2}(\mathbb{R}^N)}^2 - o(\|w\|_{W^{1,2}(\mathbb{R}^N)}^2)$ uniformly in n , so $\max_{t>0} J_n(tv_n^{i_n})$ is bounded away from zero, uniformly in n . It is easy to show that J_n is Lipschitz on bounded subsets of $W^{1,2}(\mathbb{R}^N)$, uniformly in n . Since (T_n) is bounded, this implies that t_n and $T_n - t_n$ are both bounded away from zero for large n .

By definition of v_n as a ‘‘mountain-pass type critical point’’ of J_n , we have

$$\max_{t>0} J_n(tv_n^{i_n}) \geq \max_{t>0} J_n(tv_n).$$

Using the facts that $\|v_n - \bar{v}_n\|_{W^{1,2}(\mathbb{R}^N)} \rightarrow 0$ as $n \rightarrow \infty$, and (T_n) is bounded, we have

$$\begin{aligned}
 \liminf_{n \rightarrow \infty} J_n(t_n v_n^{i_n}) &= \liminf_{n \rightarrow \infty} \max_{t > 0} J_n(t v_n^{i_n}) \\
 &\geq \liminf_{n \rightarrow \infty} \max_{t > 0} J_n(t v_n) \\
 &= \liminf_{n \rightarrow \infty} \max_{t > 0} J_n(t \bar{v}_n) \\
 &= \liminf_{n \rightarrow \infty} J_n(t_n \bar{v}_n) \\
 &= \liminf_{n \rightarrow \infty} (J_n(t_n v_n^{i_n}) + J_n(t_n v_n^{3-i_n})) \\
 &\geq \liminf_{n \rightarrow \infty} J_n(t_n v_n^{i_n}) + \liminf_{n \rightarrow \infty} J_n(t_n v_n^{3-i_n}).
 \end{aligned} \tag{3.2}$$

Now $J_n(T_n v_n^{3-i_n}) = -J_n(T_n v_n^{i_n}) \geq 0$ and $t_n < T_n$, so $J_n(t_n v_n^{3-i_n}) \geq 0$. By (3.2), $\liminf_{n \rightarrow \infty} J_n(t_n v_n^{3-i_n}) \leq 0$. Therefore $J_n(t_n v_n^{3-i_n}) \rightarrow 0$ as $n \rightarrow \infty$.

Since $J_n(w) \geq \frac{1}{\theta} \min(1, V_-) \|w\|_{W^{1,2}(\mathbb{R}^N)}^2 - o(\|w\|_{W^{1,2}(\mathbb{R}^N)}^2)$ uniformly in n , there exists $d \in (0, \liminf_{n \rightarrow \infty} t_n)$ such that $\liminf_{n \rightarrow \infty} J_n(d v_n^{3-i_n}) > 0$. Since $d < t_n$ and $J_n(d v_n^{3-i_n}) > J_n(t_n v_n^{3-i_n})$ for large n , the map $t \mapsto J_n(t v_n^{3-i_n})$ achieves a maximum at some $t'_n \in (0, t_n)$, and that maximum is bounded away from zero.

Summarizing the important facts about the mapping $t \mapsto J_n(t v_n^{3-i_n})$, we have shown that there exists $\rho > 0$ such that for large n ,

- (i) $0 < t'_n < t_n < T_n$
- (ii) (T_n) is bounded.
- (iii) $(T_n - t_n)$ is bounded away from zero.
- (iv) $J_n(t'_n v_n^{3-i_n}) > \rho > 0$
- (v) $J_n(t_n v_n^{3-i_n}) \rightarrow 0$
- (vi) $J_n(T_n v_n^{3-i_n}) \geq 0$

From (i)-(vi) it is apparent that at some $t_n^* > t'_n$, the mapping $t \mapsto J_n(t v_n^{3-i_n})$ is at once decreasing and concave upward. But this is impossible: let $n \in \mathbb{N}$ and $w \in W^{1,2}(\mathbb{R}^N) \setminus \{0\}$. Define $\psi(t) = J_n(tw)$ for $t > 0$. Then

$$\begin{aligned}
 \psi'(t) &= t \int_{\mathbb{R}^N} |\nabla w|^2 + V(z_n + \epsilon_n z) w^2 dz - \int_{\mathbb{R}^N} g(z_n + \epsilon_n z, tw) w dz \\
 &= t \left[\int_{\mathbb{R}^N} |\nabla w|^2 + V(z_n + \epsilon_n z) w^2 dz - \int_{\{w \neq 0\}} \frac{g(z_n + \epsilon_n z, tw)}{tw} w^2 dz \right].
 \end{aligned}$$

By (F5) and (2.1), $t \mapsto g(z_n + \epsilon_n z, tw)/(tw)$ is nondecreasing, so if $\psi'(t)$ ever becomes negative, ψ' is increasing for all time t after that, and the graph of ψ is concave down. Therefore the behavior of $J_n(t v_n^{3-i_n})$ as described in (i)-(vi) is impossible, and Lemma 3.1 is proven. \diamond

As mentioned before, it will be advantageous to work with the maxima of (u_{ϵ_n}) . Choose $(y_n) \subset \mathbb{R}^N$ with

$$u_{\epsilon_n}(y_n) = \max_{\mathbb{R}^N} u_{\epsilon_n}.$$

We will prove

$$\Delta V(y_n) \rightarrow \Delta_0. \tag{3.3}$$

By Lemma 3.0, $((y_n - z_n)/\epsilon_n)$ is bounded, so $y_n - z_n \rightarrow 0$. Thus (3.3) gives Proposition 2.2(ii), completing the proof of Theorem 1.1. \diamond

Along a subsequence, $y_n \rightarrow \bar{y} \in \bar{\Lambda}$. By Proposition 2.2(i), $V(\bar{y}) = V_0$. Since is not apparent that $\bar{y} \in \Lambda$, we must proceed carefully. We will redefine the v_n 's like in (2.7), by translating u_{ϵ_n} to 0 and dilating it. That is,

$$v_n(z) = u_{\epsilon_n}(y_n + \epsilon_n z). \tag{3.4}$$

Then v_n is a positive weak solution, vanishing at infinity, of the “penalized, dilated, and translated” PDE

$$-\Delta v + V(y_n + \epsilon_n z)v = g(y_n + \epsilon_n z, v).$$

Like before, (v_n) converges locally uniformly to a function v_0 . We claim that v_0 is actually a ground state maximizing at 0 of the autonomous limiting equation (2.6). Proof: As before, define χ_n by $\chi_n(z) = \chi(y_n + \epsilon z)$. As before, along a subsequence, χ_n converges weakly in L^p , for any $p > 1$, on compact subsets of \mathbb{R}^N to a function χ with $0 \leq \chi \leq 1$. Define \bar{g} by

$$\bar{g}(z, s) = \chi(z)f(s) + (1 - \chi(z))\tilde{f}(s).$$

By the argument of Proposition 2.2, taken from [3], (v_n) converges locally along a subsequence to v_0 , a ground state of $-\Delta v + V_0 v = \bar{g}(z, v)$. The functional corresponding to this equation is $\bar{J}(u) = \int_{\mathbb{R}^N} \frac{1}{2}(|\nabla u|^2 + V_0 u^2) - \bar{G}(z, u) dz$, where $\bar{G}(z, s) = \int_0^s \bar{g}(z, t) dt$. As before, in (2.10), $\underline{c} \geq \liminf_{n \rightarrow \infty} J_n(v_n) \geq \bar{J}(v_0)$, where \underline{c} is from (2.5). $\bar{J} \geq I_0$, where I_0 is the “autonomous” limiting functional from (2.4), so

$$\underline{c} \leq \max_{t>0} I_0(tv_0) \leq \max_{t>0} \bar{J}(tv_0) \leq \underline{c},$$

and v_0 is actually a ground state of (2.6). \diamond

Not only does (v_n) converge locally to v_0 , but it satisfies the following lemma.

Lemma 3.2 *With (v_n) as in (3.4), for any subsequence of (v_n) there is a radially symmetric ground state v_0 of (2.6) such that $v_n \rightarrow v_0$ uniformly along a subsequence and the v_n 's decay exponentially, uniformly in n .*

Proof: If one establishes uniform convergence, the uniform exponential decay follows readily, using a standard maximum principle argument found in [3]. Suppose the convergence is not uniform. Then there exist a subsequence of (v_n) (denoted (v_n)) and a sequence $(x_n) \subset \mathbb{R}^N$ with $|x_n| \rightarrow \infty$ and $\lim_{n \rightarrow \infty} v_n(x_n) > 0$. Let $d > 0$ with $d < v_0(0)$ and $d < \lim_{n \rightarrow \infty} v_n(x_n)$. For large n , $d < v_n(0) = u_{\epsilon_n}(z_n)$ and $d < v_n(x_n) = u_{\epsilon_n}(z_n + \epsilon_n x_n)$. Letting $w_n = z_n + \epsilon_n x_n$, we obtain $((w_n - z_n)/\epsilon_n) = (x_n)$, which is unbounded, violating Lemma 3.1.

To show $\Delta V(y_n) \rightarrow \Delta_0$, we again argue indirectly. Suppose otherwise. Then, along a subsequence, $y_n \rightarrow \bar{y} \in \bar{\Lambda}$ with

$$\Delta V(\bar{y}) > \Delta_0. \quad (3.5)$$

For $x \in \mathbb{R}^N$, define the translation operator τ_x by $\tau_x u(z) = u(z - x)$, that is, $\tau_x u$ is u translated by x . Assume for convenience, and without loss of generality, that

$$0 \in \Lambda, \quad V(0) = V_0, \quad \text{and} \quad \Delta V(0) = \Delta_0.$$

We will prove that for large n ,

$$\sup_{t>0} J_{\epsilon_n}(t\tau_{-y_n/\epsilon_n} u_{\epsilon_n}) < J_{\epsilon_n}(u_{\epsilon_n}) = \sup_{t>0} J_{\epsilon_n}(tu_{\epsilon_n}), \quad (3.6)$$

recalling the definition of J_ϵ in (2.2), and how v_n is defined from u_{ϵ_n} in (3.4). That is, translating tu_{ϵ_n} back to the origin reduces the value of $J_{\epsilon_n}(tv_n)$ because V has lesser concavity at the origin. This occurs even though shrinking ϵ reduces the difference in concavity. (3.6) contradicts the definition of u_{ϵ_n} .

Pick $T > 1$ large enough so that for large n , $J_n(Tv_n) = \epsilon_n^{-N} J_{\epsilon_n}(Tu_{\epsilon_n}) < 0$. This is possible by the argument of (3.1). Now (3.6) is equivalent to

$$\sup_{0 \leq t \leq T} J_{\epsilon_n}(t\tau_{-y_n} u_{\epsilon_n}) < \sup_{0 \leq t \leq T} J_{\epsilon_n}(tu_{\epsilon_n}).$$

To prove the above, it will suffice to prove the stronger fact that for large n , for all $t \in (0, T)$,

$$J_{\epsilon_n}(tu_{\epsilon_n}) > J_{\epsilon_n}(t\tau_{-y_n} u_{\epsilon_n}).$$

Now, along a subsequence, $v_n \rightarrow v_0$ uniformly, so by the definition of v_n as a dilation of $\tau_{-y_n} u_{\epsilon_n}$ ((3.4)), $u_{\epsilon_n} \rightarrow 0$ uniformly on $\mathbb{R}^N \setminus \Lambda$ as $n \rightarrow \infty$. Thus for large n and $0 \leq t \leq T$, the definition of G gives $G(z, t\tau_{-y_n} u_{\epsilon_n}(z)) = F(t\tau_{-y_n} u_{\epsilon_n}(z))$ for all $z \in \mathbb{R}^N$, so

$$\begin{aligned} & J_{\epsilon_n}(tu_{\epsilon_n}) - J_{\epsilon_n}(t\tau_{-y_n} u_{\epsilon_n}) \\ &= \int_{\mathbb{R}^N} \frac{1}{2} t^2 (|\nabla u_{\epsilon_n}(z)|^2 + V(z)u_{\epsilon_n}(z)^2) - G(z, tu_{\epsilon_n}(z)) \, dz \\ &\quad - \left[\int_{\mathbb{R}^N} \frac{1}{2} t^2 (|\nabla \tau_{-y_n} u_{\epsilon_n}(z)|^2 + V(z)\tau_{-y_n} u_{\epsilon_n}(z)^2) - F(t\tau_{-y_n} u_{\epsilon_n}(z)) \, dz \right] \\ &\geq \frac{1}{2} t^2 \int_{\mathbb{R}^N} V(z)(u_{\epsilon_n}(z)^2 - u_{\epsilon_n}(z + y_n)^2) \, dz \end{aligned}$$

$$\begin{aligned}
 & + \int_{\mathbb{R}^N} F(tu_{\epsilon_n}(z + y_n) - F(tu_{\epsilon_n}(z)) dz \\
 = & \frac{1}{2}t^2 \int_{\mathbb{R}^N} (V(z + y_n) - V(z))u_{\epsilon_n}(z + y_n)^2 dz \\
 = & \frac{1}{2}t^2\epsilon_n^N \int_{\mathbb{R}^N} (V(y_n + \epsilon_n z) - V(\epsilon_n z))u_{\epsilon_n}(\epsilon_n z + y_n)^2 dz \\
 = & \frac{1}{2}t^2\epsilon_n^N \int_{\mathbb{R}^N} (V(y_n + \epsilon_n z) - V(\epsilon_n z))v_n(z)^2 dz.
 \end{aligned}$$

For $n = 1, 2, \dots$, define $h_n : \mathbb{R} \rightarrow \mathbb{R}$ by

$$h_n(t) = \int_{\mathbb{R}^N} (V(y_n + tz) - V(tz))v_n^2 dz.$$

Since $h_n(\epsilon_n) = \int_{\mathbb{R}^N} (V(y_n + \epsilon_n z) - V(\epsilon_n z))v_n^2 dz$, we must prove that for large n ,

$$h_n(\epsilon_n) > 0. \tag{3.7}$$

Assume without loss of generality that Λ was chosen so that there exists $\rho > 0$ with

$$\inf_{N_\rho(\Lambda)} V = V_0, \tag{3.8}$$

where $N_\rho(\Lambda) = \{x \in \mathbb{R}^N \mid \exists y \in \Lambda \text{ with } |y - x| < \rho\}$. We will prove the following facts about h_n :

Lemma 3.3 *For some $\beta > 0$, for large n ,*

- (i) $h_n \in C^2(\mathbb{R}^+, \mathbb{R})$
- (ii) $h_n(0) \geq 0$
- (iii) $|h'_n(0)|^2 \leq o(1)h_n(0)$
- (iv) $h''_n(0) > \beta$
- (v) h''_n is locally Lipschitz on \mathbb{R}^+ , uniformly in n .

Here $o(1) \rightarrow 0$ as $n \rightarrow \infty$. Before proving Lemma 3.3, let us prove how it gives (3.7). By (iv)-(v), there exists $d > 0$ such that for large n and $0 \leq t \leq d$, $h''_n(t) > \beta/2$. For $t \in [0, d]$, a Taylor's series expansion shows that for large n ,

$$h_n(t) \geq h_n(0) + h'_n(0)t + \frac{\beta}{4}t^2 \equiv l_n(t). \tag{3.9}$$

If $h_n(0) = 0$, then by Lemma 3.3(iii), $h'_n(0) = 0$, so (3.9) implies that $h_n(t) > 0$ for all $t \in (0, d)$, giving (3.7) if n is large enough that $\epsilon_n < d$. If $h_n(0) > 0$, then by elementary calculus, l_n attains a minimum value at $t = -2h'_n(0)/\beta$, and the minimum value is

$$\min_{\mathbb{R}} l_n = l_n(-2h'_n(0)/\beta) = h_n(0) - h'_n(0)^2/\beta \geq (1 - o(1))h_n(0),$$

where $o(1) \rightarrow 0$ as $n \rightarrow \infty$. For large n , if $h_n(0) > 0$ then $l_n(t) > 0$ for all $t \in \mathbb{R}$, so $h_n(t) > 0$ for all $t \in (0, d)$ for large n , implying (3.7) if n is large enough so that $\epsilon_n < d$.

Proof of Lemma 3.3 Statement (ii) is trivial, since $h_n(0) = (V(y_n) - V_0) \int_{\mathbb{R}^N} v_n^2$, and since $z_n \in \bar{\Lambda}$ and $y_n - z_n \rightarrow 0$, (3.8) implies $V(y_n) \geq V_0$ for large n . (i) and (v) follow from Leibniz's Rule, $(V_1) - (V_2)$, and the fact that the v_n 's decay exponentially, uniformly in n . For $j = 1, 2$,

$$h_n^{(j)}(t) = \int_{\mathbb{R}^N} \sum_{|\alpha|=j} (D^\alpha V(y_n + tz) - D^\alpha V(tz)) z^\alpha v_n(z)^2 dz.$$

Since (V2) holds, v_n decays exponentially, uniformly in n , $y_n \rightarrow \bar{y}$, and v_0 is radially symmetric, we have

$$\begin{aligned} h_n''(0) &= \int_{\mathbb{R}^N} \sum_{|\alpha|=2} (D^\alpha V(y_n) - D^\alpha V(0)) z^\alpha v_n(z)^2 dz \\ &\rightarrow \int_{\mathbb{R}^N} \sum_{|\alpha|=2} (D^\alpha V(\bar{y}) - D^\alpha V(0)) z^\alpha v_0(z)^2 dz \\ &= \int_{\mathbb{R}^N} \sum_{i=1}^N (D^{ii} V(\bar{y}) - D^{ii} V(0)) z_i^2 v_0(z)^2 dz \\ &= \int_{\mathbb{R}^N} \sum_{i=1}^N (D^{ii} V(\bar{y}) - D^{ii} V(0)) \frac{1}{N} |z|^2 v_0(z)^2 dz \\ &= \frac{1}{N} (\Delta V(\bar{y}) - \Delta V(0)) \int_{\mathbb{R}^N} |z|^2 v_0(z)^2 dz > 0 \end{aligned}$$

by assumption (3.5). Since Lemma 3.3(v) holds, we have Lemma 3.3(iv).

To prove Lemma 3.3(iii), we will need the following calculus lemma:

Lemma 3.4 *Let $U \subset \mathbb{R}^N$ and $r > 0$. Let $V \in C^2(N_r(U), \mathbb{R})$ with $\inf_{N_r(U)} V \equiv V_0 > -\infty$, $|\nabla V|$ bounded on $N_r(U)$, and D^2V Lipschitz on $N_r(U)$. Then there exists $C > 0$ with*

$$|\nabla V(z)|^2 \leq C(V(z) - V_0) \tag{3.10}$$

for all $z \in U$.

Proof: let $B > 0$ with $|D^2V(z)\xi \cdot \xi| \leq B$ for all $\xi \in \mathbb{R}^N$ with $|\xi| = 1$. Also let B be big enough so

$$B > |\nabla V(z)|/r$$

for all $z \in U$. Pick $z \in U$. If $|\nabla V(z)| = 0$, then (3.10) is obvious. Otherwise, let $d = |\nabla V(z)|/B < r$. Define $\varphi(t) = V(z - t\nabla V(z)/|\nabla V(z)|)$ for $t \in [0, d]$. φ is C^2 , $\varphi(0) = V(z)$, and $\varphi'(0) = -|\nabla V(z)|$. By choice of B and the fact that $B_d(z) \subset N_r(U)$, $|\varphi''(t)| \leq B$ for all $t \in [0, d]$. Taylor's theorem gives

$$\varphi(d) - \varphi(0) = \varphi'(0)d + \varphi''(\xi) \frac{d^2}{2} \leq -|\nabla V(z)|d + Bd^2/2 = -\frac{|\nabla V(z)|^2}{2B}.$$

Also $\varphi(d) \geq V_0$ because $B_d(z) \subset N_r(U)$. Therefore,

$$\frac{|\nabla V(z)|^2}{2B} \leq \varphi(0) - \varphi(d) \leq V(z) - V_0.$$

Lemma 3.4 is proven. \diamond

To prove Lemma 3.3(iii), first note that, by the radial symmetry of v_0 , the uniform exponential decay of v_n , and the uniform convergence $v_n \rightarrow v_0$,

$$\begin{aligned} |h'_n(0)| &= |(\nabla V(y_n) - \nabla V(0)) \cdot \int_{\mathbb{R}^N} z v_n^2 dz| \\ &= |\nabla V(y_n) \cdot \int_{\mathbb{R}^N} z v_n^2 dz| \\ &= |\nabla V(y_n) \cdot \int_{\mathbb{R}^N} z v_0^2 dz + \nabla V(y_n) \cdot \int_{\mathbb{R}^N} z (v_n^2 - v_0^2) dz| \\ &= |\nabla V(y_n) \cdot \int_{\mathbb{R}^N} z (v_n^2 - v_0^2) dz| \\ &\leq |\nabla V(y_n)| \left| \int_{\mathbb{R}^N} z (v_n^2 - v_0^2) dz \right| \\ &\leq o(1) |\nabla V(y_n)|, \end{aligned}$$

so Lemma 3.4 implies

$$\begin{aligned} |h'_n(0)|^2 &\leq o(1) |\nabla V(y_n)|^2 \leq o(1) (V(y_n) - V_0) \\ &\leq o(1) (V(y_n) - V_0) \int_{\mathbb{R}^N} v_n^2 \\ &= o(1) h_n(0), \end{aligned}$$

since $\int_{\mathbb{R}^N} v_n^2$ is bounded away from zero. Lemma 3.3(iii) is proven. Thence follow (3.7), (3.3), Proposition 2.2, and Theorem 1.1.

Remarks: Besides the results cited in the introduction, many important results for equations of type (1.1) have been found recently. For instance, the work in [3]-[5] suggests that Theorem 1.1 could be strengthened by working on a smaller domain than \mathbb{R}^N , or by weakening the hypotheses on V . It is natural to try to extend Theorem 1.1 to cases where V is not C^2 , or to the case where the second derivatives of V do not provide a condition like (V4), but higher-order derivatives do.

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