

Slosh Damping Using Magneto- Active Propellant Management Device

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Issues

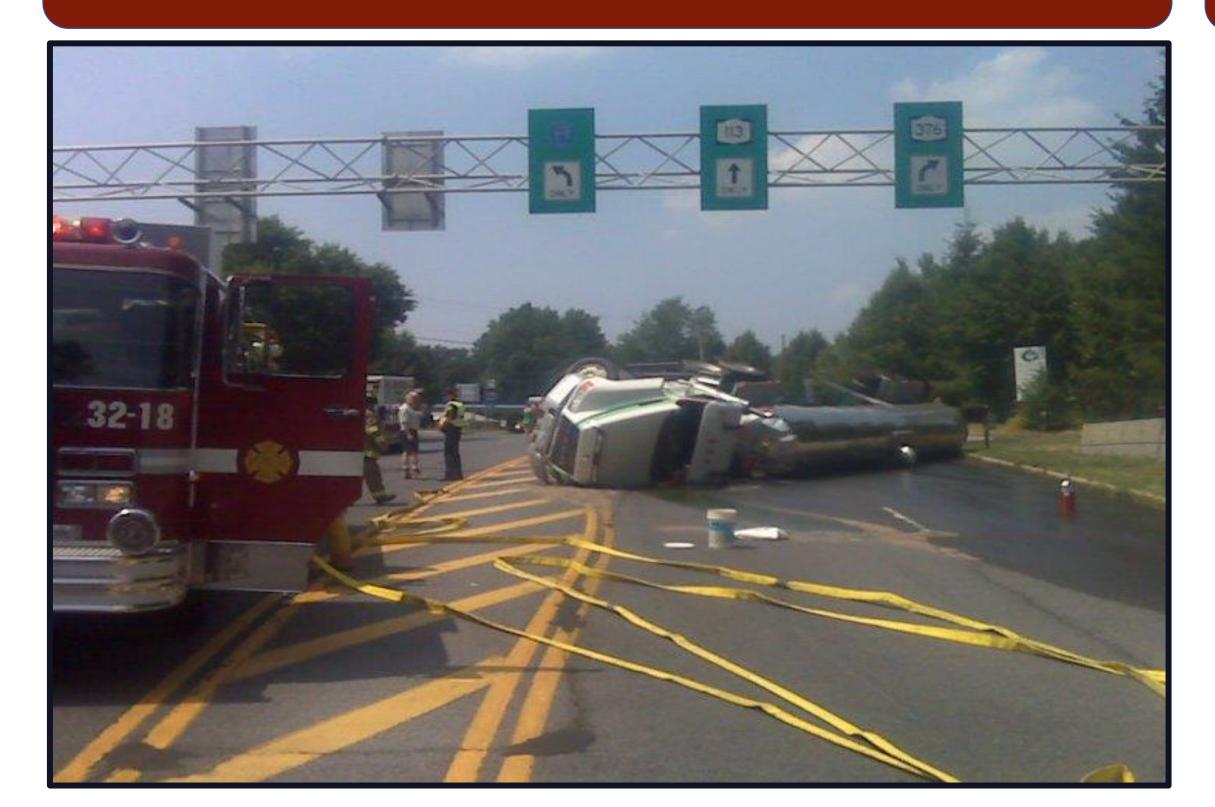


Figure 1. Tanker Accidents due to uncontrolled moment



Figure 2. A trajectory deviation of the rocket (Falcon, 2007)



Figure 3. Internal cracks in the Volvo bus fuel tank

Liquid Slosh

Movement of free surface of a liquid within a container or a propellant tank.

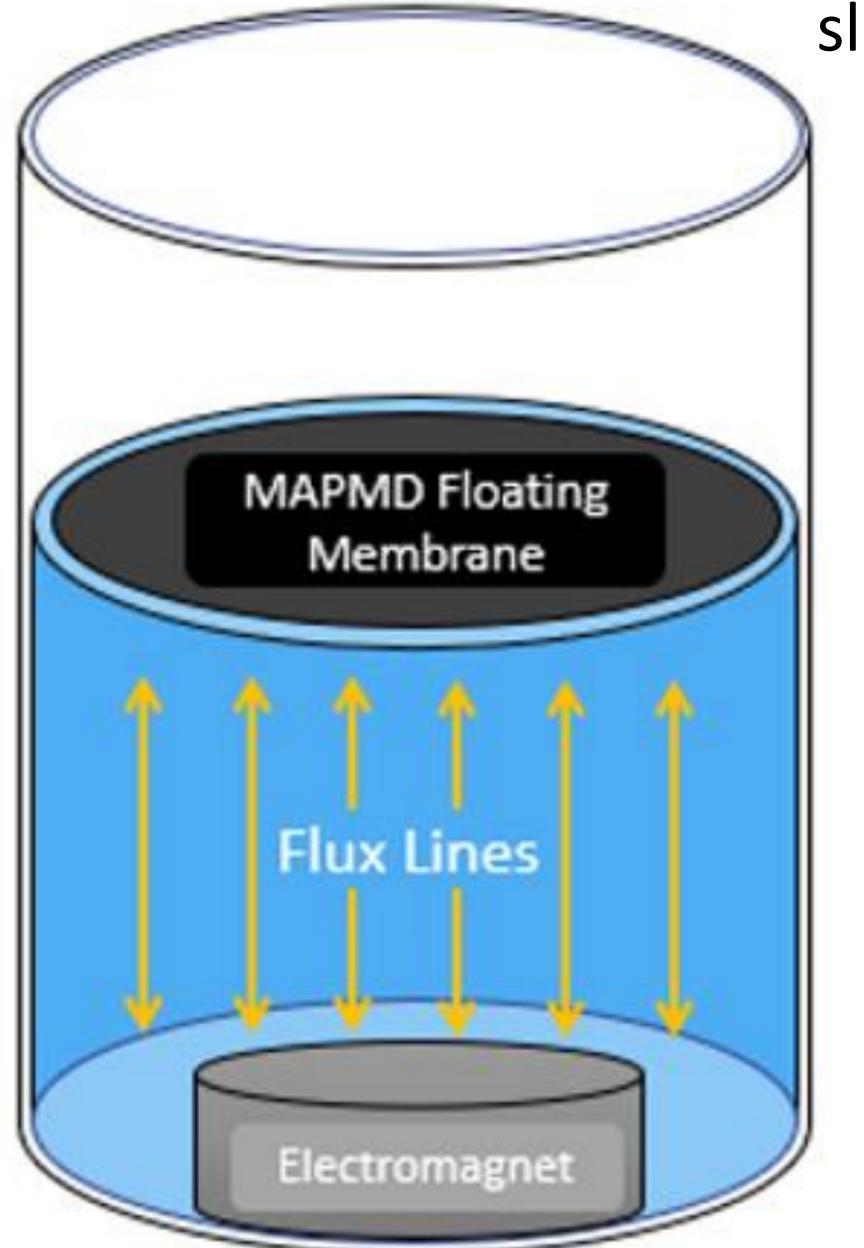
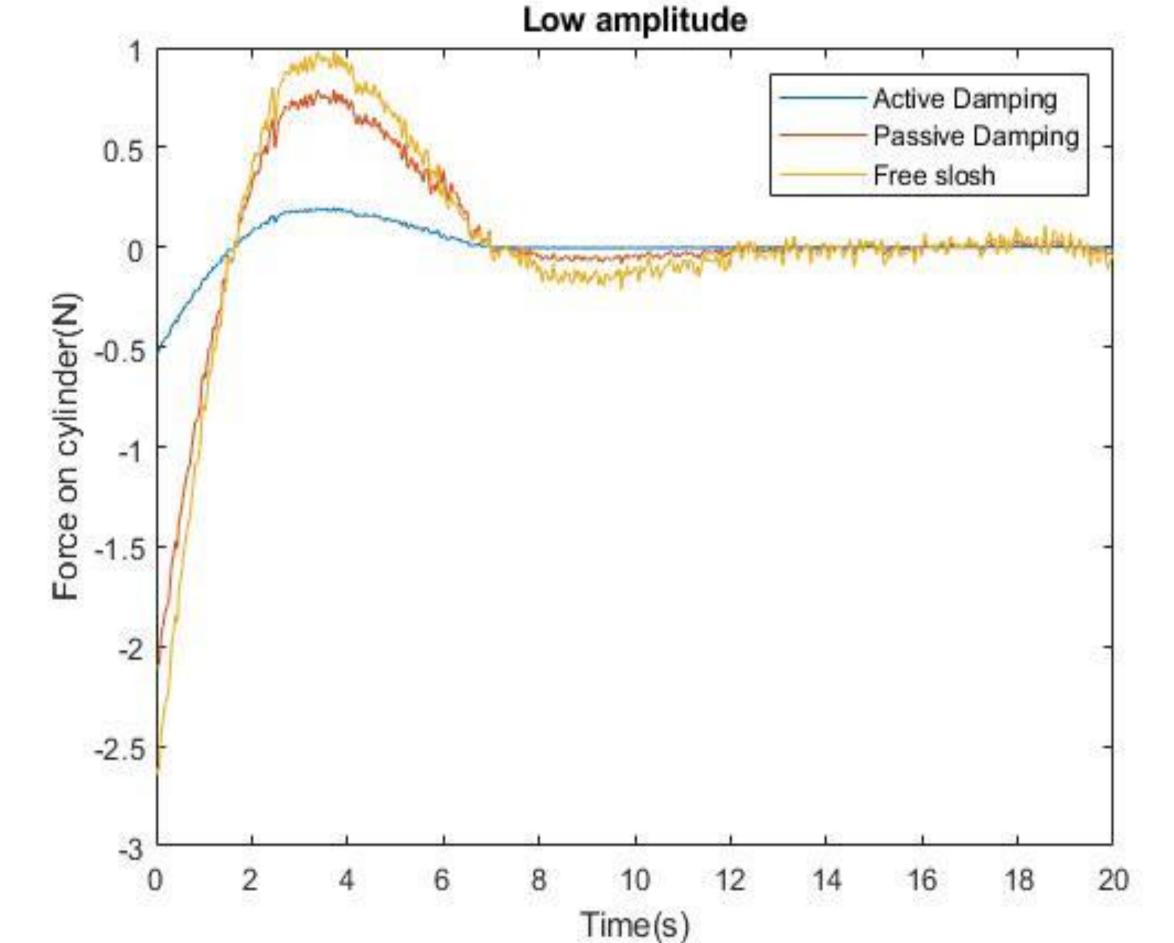
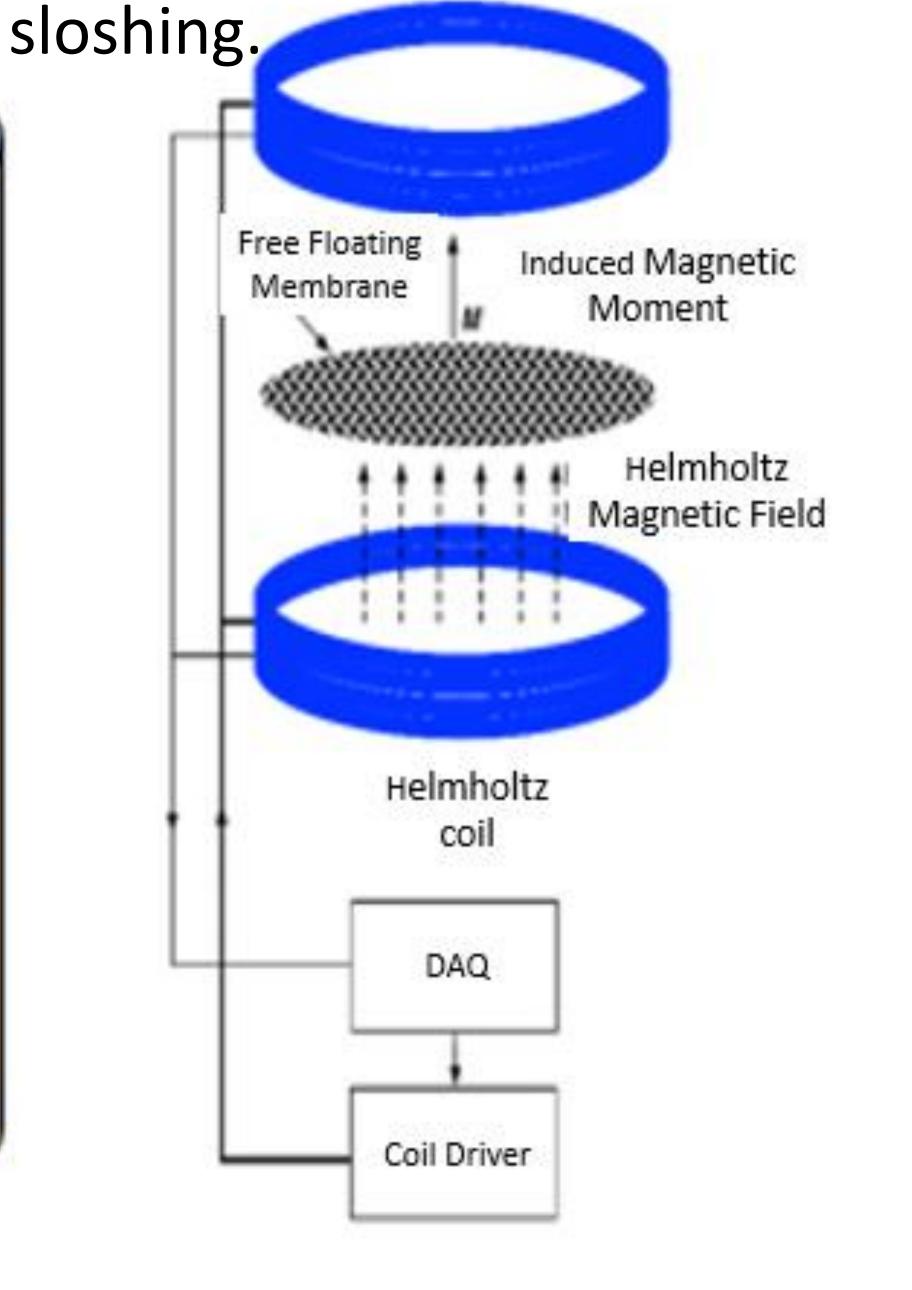


Figure 4. For MAPMD active condition, no visible deviation and synchronous peaks in the seen. This can be attributed to the fact that slosh wave amplitudes are low in this condition and damping can be attained at 6s. For inactive and free slosh condition, deviations in the curve can be seen even after 20s.



Working Principle

Sloshing in the propellant tank is controlled electromagnetic which membrane creates downward force reduce



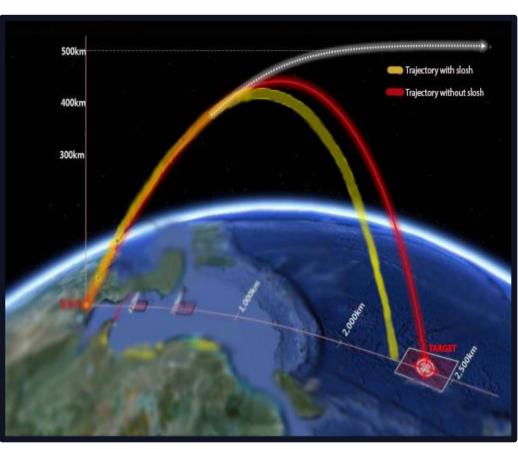
Space Mission (19) United States

Applications



Tanker

Oil train



Aircraft Fuel tank





Marine



US 2016/0203901 A1 US 2016/0318708 A1

